



<b>SUPERVISOR INFORMATION</b>	
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Department	Department of Electrical and Computer Engineering
Field(s) of research	Robotics and IoT
<b>PROJECT PROPOSAL</b>	
Title (optional)	Phenotyping Robot for Sustainable Management of Permanent Woody Crops
Brief project description	
<p>Remote sensing has revolutionized precision agriculture by enabling data-driven decision-making. However, its effectiveness is often limited by coarse spatial resolution and by the constraints of emerging production systems such as agrivoltaics and controlled-environment agriculture. These contexts demand high-resolution, proximal phenotyping, which remains a labor-intensive and time-consuming task when conducted manually. This project aims to develop and validate robotic solutions for autonomous proximal phenotyping, enhancing the Modular-E robotic platform from INESC TEC with manipulation and spectral sensing modules. The research will focus on achieving robust, all-weather operation and safe interaction with soft and moving plant tissues in open-field conditions.</p> <p>The expected outcome is a new generation of adaptive robotic phenotyping systems capable of delivering high-resolution, real-time plant and canopy data, bridging the gap between field robotics and digital crop intelligence to support sustainable and precise management of permanent crops.</p>	